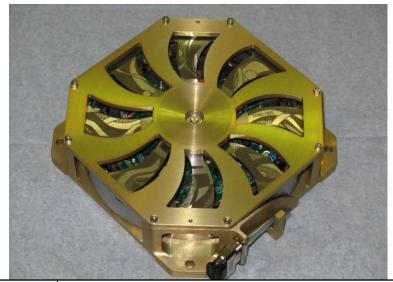
Microsatellite Reaction Wheels (RW3-1.0)



| Momentum | Nominal: 1.0 Nms |
|-----------------------------|--|
| Torque | ±50 mNm at 1 Nms (at 28 V supply) |
| Control Mode | Speed, torque or current with built-in control CPU |
| Command / Telemetry | Two RS-485 plus one CAN, or one RS-485 plus two CAN ±36 V fault tolerant |
| Mechanical | Dimensions: 150 mm x 140 mm x 42 mm Mass: 970 g |
| Supply Voltage | Nominal: 24 V to 34 V Maximum: 50 V Redundant input buses, reverse polarity protected, shorted bus protected |
| Supply Power (in vacuum) | 46.7 W @ 1.0 Nms, +40 mNm 15.1 W @ 1.0 Nms, steady state 2.4 W @ 0.2 Nms, steady state −29.1 W @ 1.0 Nms, −100 mNm regenerative braking |
| Environment | Thermal: −40°C to +70°C (operating) Vibration: >14 g _{RMS,} Radiation: >20 krad dose |
| Reliability | Diamond coated hybrid ball bearings Redundant motor windings Radiation lot-screened parts on all flight models |
| Heritage | 52 Units on-orbit. First launch June 2016. Demonstrated stability for 1 m GSD Earth-observing spacecraft |
| Price | US\$60,000 each |



Rev 2019a RW3-1.0

